

# Aggregating From Multiple Target-Shifted Sources

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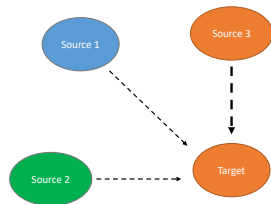
**Changjian Shui**, Zijian Li, Jiaqi Li, Christian Gagné, Charles X.Ling, Boyu Wang

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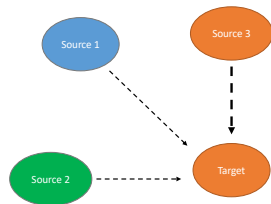
# Multiple-Source Domain Adaptation

- Learning a target domain with limited or even no label information through multiple *related* sources.



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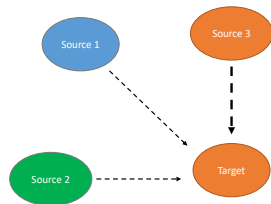
- Learning a target domain with limited or even no label information through multiple *related* sources.
- Widely applied in image segmentation, crowd sourcing and personal medicine.



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- Learning a target domain with limited or even no label information through multiple *related* sources.
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- Key Question:

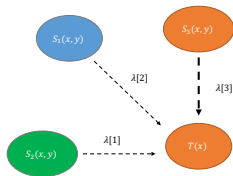
How to select relevant sources to avoid negative transfer ?



## Selection through domain similarity

Conventional theories in multi-source domain adaptation:

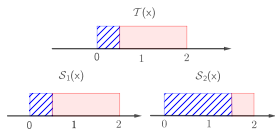
$$R_{\mathcal{T}}(h) \leq \frac{1}{T} \sum_{t=1}^T R_{S_t}(h) + \sum_{t=1}^T \lambda[t] \text{dist}(\mathcal{S}_t(x), \mathcal{T}(x))$$



- $\lambda$  is a simplex, measuring source-target relations.
- If marginal distribution distance  $\text{dist}(\mathcal{S}_t(x), \mathcal{T}(x))$  is small, assigning higher  $\lambda[t]$ .

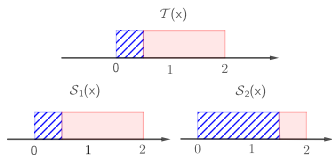
## Limitation of adopting $\text{dist}(\mathcal{S}_t(x), \mathcal{T}(x))$

- $\text{dist}(\mathcal{S}_1(x), \mathcal{T}(x)) = \text{dist}(\mathcal{S}_2(x), \mathcal{T}(x))$
- $\lambda[1] = \lambda[2]$
- $\mathcal{S}_2$  is a **unreliable** source: label proportion between sources-target is different.



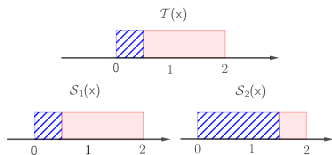
Research Goal: Leveraging from different label ( $y$ )-shifted sources.

# One Solution



- $\text{dist}(\mathcal{S}_1(x|y), \mathcal{T}(x|y)) < \text{dist}(\mathcal{S}_2(x|y), \mathcal{T}(x|y))$

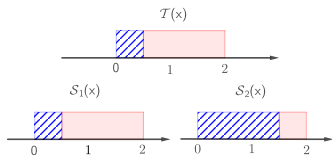
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- Assigning higher  $\lambda[1]$  for  $\mathcal{T}$ .



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- Assigning higher  $\lambda[1]$  for  $\mathcal{T}$ .
- Adopting the similarity of *conditional* distribution is more reliable.

## Our Contributions

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- Analyze multi-sources domain adaptation with  $\mathcal{S}_t(y) \neq \mathcal{T}(y)$ ,  
 $\mathcal{S}_t(x|y) \neq \mathcal{T}(x|y)$

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 $\mathcal{S}_t(x|y) \neq \mathcal{T}(x|y)$
- A theoretically grounded approach with compelling empirical results, compared with modern baselines.

# Our Contributions

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- Analyze multi-sources domain adaptation with  $\mathcal{S}_t(y) \neq \mathcal{T}(y)$ ,  $\mathcal{S}_t(x|y) \neq \mathcal{T}(x|y)$
- A theoretically grounded approach with compelling empirical results, compared with modern baselines.
- A **unified** method for handling different scenarios, where previous works generally treated as separate problems.

# Unified Approach

**Table 1:** Three multi-source domain adaptation (DA) scenarios

	Target label	$\text{supp}(\mathcal{S}_t(y)) = \text{supp}(\mathcal{T}(y))$	Additional Assumption
DA Limited label	✓	✓	✗
Unsupervised DA	✗	✓	✓
Partial Unsupervised DA	✗	✗	✓

- Require additional assumptions in unsupervised scenarios when label and conditional distribution shift.
- Partial Unsupervised DA  $\text{supp}(\mathcal{T}(y)) \subseteq \text{supp}(\mathcal{S}_t(y))$

Thank You